

## Autonomous Detection Vehicle

- Autonomous route investigation and hazard marking
- Fundamentally an appliqué kit for a vehicle
- Leverage previous work by Night Vision Laboratory



## Convoy Logistics

- Kit-based system for Tactical Wheeled Vehicles
- Automated leader-follower
- User assessment at Fort Hood in the September – October timeframe



## Robotic Wingman

- Large armed robotic platform assumes role as a member of squad / formation
- Leverage existing ARDEC, AMREC, CERDEC technologies and Fort Hood rodeo for target acquisition and engagement capability



## Robotics Rodeo

- Input from Army needs (ONS)
- Demonstration of related state of the art technologies
- Provide user and SME feedback to industry

## Persistent Stare

- Small robot with autonomous navigation to perform recon and surveillance
- Utilize robotic rodeo to demonstrate vendor capabilities



## VOIED

## Defeat

- Capability for autonomous VOIED defeat
- Utilize robotic rodeo to demonstrate vendor capabilities
- HMMWV and M113 target platforms